

aPR33A3

CPU Serial Mode (C1.1) Datasheet

FEATURES

- Operating Voltage Range: 3V ~ 6.5V
- Single Chip, High Quality Audio/Voice Recording & Playback Solution
 - No External ICs Required
 - Minimum External Components
- User Friendly, Easy to Use Operation
 - Programming & Development Systems Not Required
- 170/ 340/ 680 sec. Voice Recording Length in aPR33A3
- Powerful 16-Bits Digital Audio Processor.
- Nonvolatile Flash Memory Technology
 - No Battery Backup Required
- External Reset pin.
- Powerful Power Management Unit
 - Very Low Standby Current: 1uA
 - Low Power-Down Current: 15uA
 - Supports Power-Down Mode for Power Saving
- Built-in Audio-Recording Microphone Amplifier
 - No External OPAMP or BJT Required
 - Easy to PCB layout
- Configurable analog interface
 - Differential-ended MIC pre-amp for Low Noise
 - High Quality Line Receiver
- High Quality Analog to Digital and PWM module
 - Resolution up to 16-bits
- Up To Maximum 1024 Voice Sections controlled through 5 pins only
- Built-in Memory-Management System



DESCRIPTION

Today's consumers demand the best in audio/voice. They want crystal-clear sound wherever they are in whatever format they want to use. APLUS delivers the technology to enhance a listener's audio/voice experience.

The aPR33A series are powerful audio processor along with high performance audio analog-to-digital converters (ADCs) and digital-to-analog converters (DACs). The aPR33A series are a fully integrated solution offering high performance and unparalleled integration with analog input, digital processing and analog output functionality. The aPR33A series incorporates all the functionality required to perform demanding audio/voice applications. High quality audio/voice systems with lower bill-of-material costs can be implemented with the aPR33A series because of its integrated analog data converters and full suite of quality-enhancing features such as sample-rate convertor.

The aPR33A series C1.X is specially designed for simple CPU interface, user can record or playback up to 1024 voices by 5 I/Os only. This mode built in one complete memory-management system. The control side doesn't need to be burdened complicated memory distribution problems and it only needs to be through a simple instruction to proceed the audio/voice recording & playback so it largely shorten the developing time. Meanwhile, Chip provides the power-management system too. Users can let the chip enter power-down mode when unused. It can effectively reduce electric current consuming to 15uA and increase the using time in any projects powered by batteries.





PIN CONFIGURATION



SOP Package



PIN DESCRIPTION

Pin Names	Pin No	TYPE	Description
VDDP	8		
VDD	10		
VDDA	18		Positive power supply.
VDDL	24		
VSSP	5		
VSSL	11		Power ground.
VSSA	17		
Vldo	25		Internal LDO output.
Vcore	16		Positive power supply for core.
Vref	19		Reference voltage.
Vсм	20		Common mode voltage.
Rosc	26	INPUT	Oscillator resistor input.
RSTB	27	INPUT	Reset. (Low active)
SRSTB	28	INPUT	System reset, pull-down a resistor to the VSSL.
MIC+	21		Microphone differential input
MIC-	22	INFUT	
MICG	23	OUTPUT	Microphone ground.
VOUT2	6		DW/M output to drive apacker directly
VOUT1	7	UUIPUI	Priviti output to drive speaker directly.
/CS	15	INPUT	Chip select. (Low active)
SCK	3	INPUT	Serial clock.
SDI	9	INPUT	Serial data input.
SDO	4	OUTPUT	Serial data output.
/BUSY	14	OUTPUT	System busy output.
/RESERVE	13	OUTPUT	Output reserve.



CONNECTION DIAGRAM





SERIAL COMMAND

The aPR33A series C1.X is specially designed for simple CPU interface. Chip is controlled by command sent to it from the host CPU. The /CS pin is used to select chip. The SCK and SDI pin are used to input command word into the chip while SDO and BUSY as output from the chip to the host CPU for feedback response.

Command input into the chip contains 16-bit data and list the command format & summarize the available commands as below:



Command	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
STOP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
DELETE	0	0	0	1	0	0				Voic	e No	In Bi	nary			
REC	0	0	1	0	0	0				Voic	e No	In Bi	nary			
PLAY	0	0	1	1	0	0				Voic	e No	In Bi	nary			
PUP	1	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0
PDN	1	0	1	1	0	0	1	0	0	0	0	0	0	0	0	0
FORMAT	1	0	1	0	0	1	0	1	1	0	1	0	0	1	0	1



• REC

The REC command is used to start record the voice to the specified voice number.

In the REC command, the bit-15 ~ bit-10 is 001000 in binary, and the bit-9 ~ bit-0 is the voice number in binary. Up to 1024 voice numbers user can specify.

After the REC command sent, the /BUSY pin will be drove low and playback "beep" tone to indicate the record operation starting.

During the record operating, the /BUSY pin will keep driving low, and any command except STOP will be ignored.

The record operation will continue until users send STOP command or full of memory, the /BUSY pin will be released and playback "beep" tone 2 times to indicate the record operation finished.

If the specified voice number already exist voice data or the memory is full, the /BUSY pin will not drive to low and execute REC operating. User can use the DELETE command to clear specified voice number before REC command.

/CS	٦	
SCK		
SDI	0 0 1 0 0 0 Voice No. In Binary	
SDO		
/BUSY		



PLAY

The PLAY command is used to start playback the voice in the specified voice number.

In the PLAY command, the bit-15 \sim bit-10 is 001100 in binary, and the bit-9 \sim bit-0 is the voice number in binary. Up to 1024 voice numbers user can specify.

After the PLAY command sent, the /BUSY pin will be drove low to indicate the playback operation starting.

During the playback operating, the /BUSY pin will keep drive low, and any command except STOP will be ignored.

The playback operation will continue until users send STOP command or end of voice, the /BUSY pin will be released to indicate the record operation finished.

If the specified voice number is empty, it will not drive /BUSY to low and playback.

/CS	7	
SCK		
SDI	0 0 1 1 0 0 Voice No. In Binary	
SDO		
/BUSY		

• STOP

The STOP command is used to stop current operation.

After the STOP command sent, the /BUSY pin will be released to indicate end of the current operation.

The STOP command is effective only in playing or recording.

/cs		
scк _		
SDI _	0 0 0 0 0 0 0 0 0 0 0 0 0 0	
SDO		
/BUSY _		



• DELETE

The DELETE command is used to delete the voice in the specified voice number.

In the DELETE command, the bit-15 ~ bit-10 is 000100 in binary, and the bit-9 ~ bit-0 is the voice number in binary. Up to 1024 voice numbers user can specify.

After the DELETE command sent, the /BUSY pin will be drove low to indicate the delete operation starting. When delete operation is finished, the /BUSY pin will be released.

The memory space in the specified voice number will be release after delete operation, user can get more free space by delete unused voice.

/cs	1	
scк		
SDI -	0 0 0 1 0 0 Voice No. In Binary	
SDO		
/BUSY		



• PDN

The PDN command is used to enter the power-down mode.

After the PDN command sent, the /BUSY pin will be drove low to indicate the power-down operation starting. When chip is in the power-down mode, the /BUSY pin will be released.

During chip in the sleep mode, the current consumption is reduced to IPDN and any command except PUP will be ignored.

/CS	7	
scк		
SDI		
SDO		
/BUSY		

• PUP

The PUP command is used to power up from sleep mode.

After the PUP command sent, the /BUSY pin will be drove low to indicate the power up operation starting. When chip is in the idle mode, the /BUSY pin will be released. User can execute REC, PLAY or DELETE, or other command in idle mode.

/CS	٦	
SCK		
SDI		
SDO		
/BUSY		

• FORMAT

The FORMAT command is used to restore memory to factory state.

After the FORMAT command sent, the /BUSY pin will be drove low to indicate the format operation starting. When format operation is finished, the /BUSY pin will be released.

All of the voice in the memory will be clear after execute format operation.

	Γ
SDI1_0_1_0_1_0_1_1_0_1_0_1_0	1
SDO	
/BUSY	



VOICE INPUT

The aPR33A series supported single channel voice input by microphone or line-in. The following fig. showed circuit for different input methods: microphone, line-in and mixture of both.



(A) Microphone









aPR33AX_C1

(C) Microphone + Line-In



VOICE OUTPUT

The aPR33A series support 2 voice output mode, PWM and DAC.

The PWM mode use VOUT1 and VOUT2 pin to drive speaker directly without external components to save cost.

The DAC mode use VOUT2 pin to output current signal. User can use the signal to drive audio amplifier or mix with other components in their applications to provide larger voice volume.

The following fig. show circuit for different output methods: PWM, DAC, DAC with transistor, DAC with audio amplifier AP4890B.



(A) PWM



(C) DAC with transistor





(D) DAC with audio amplifier AP4890B

RESET

aPR33A series can enter standby mode when RSTB pin drive to low. During chip in the standby mode, the current consumption is reduced to IsB and any operation will be stopped, user also can not execute any new operate in this mode.

The standby mode will continue until RSTB pin goes to high, chip will be started to initial, and playback "beep" tone to indicate enter idle mode.

User can get less current consumption by control RSTB pin specially in some application which concern standby current.





EXAMPLE

The aPR33DB is one of the simplest solutions for achieve serial command mode demo. The circuit board already includes the peripheral circuit which containing microphone. Developers only need to notice how to connect with their development environment. It can effectively decrease the time of circuit connecting & any possible mistakes. Below figure shows how to connect aPR33DB with external host board in serial command mode :





The below example C code display all the operating instructions. Developers can evaluate any possible operating ways and voice quality in the shortest time :

//==							
// I/O Define							
//=-=-=-=-=-=-=-=-=-=-=-=	=-						
// P_CS : aPR33Ax /C	CS pin.						
// P_SCK : aPR33Ax SC	CK pin.						
// P_DO : aPR33Ax DO	O pin.						
// P_DI : aPR33Ax DI	I pin.						
// P_BUSY: : aPR33Ax /H	BUSY pin.						
// KEY_REC : Key for re	ecord, high active.						
// KEY_PLAY: Key for pl	layback, high active						
//							
// Type Define							
//=-=-=-=-=-=-=-=-=-=-=-=-=	=-=						
// unsigned char: 1-byt	te.						
// unsigned int : 2-byt	tes.						
typedef union	UTYPE						
{							
unsigned int	Tunsigned int;	// Dual-byte					
struct							
{							
unsigned	TBIT0:1;						
unsigned	TBIT1:1;						
unsigned	TBIT2:1;						
unsigned	TBIT3:1;						
unsigned	TBIT4:1;						
unsigned	TBIT5:1;						
unsigned	TBIT6:1;						
unsigned	TBIT7:1;						
unsigned	TBIT8:1;						
unsigned	TBIT9:1;						
unsigned	TBIT10:1;						
unsigned	TBIT11:1;						

TBIT12:1; unsigned unsigned TBIT13:1; unsigned TBIT14:1; unsigned TBIT15:1; }; }UTYPE; //===== // Prototype void CS(BOOL Value) { P CS =Value; } { P_SCK=Value; Delay_500nS(); } SCK(BOOL Value) void SDO(BOOL Value) { P_DO =Value; Delay_500nS(); } void BOOL SDI() { return(P_DI); } unsigned int SendCmd(unsigned int Value) { UTYPE TxData, RxData; //-----TxData.Tunsigned int = Value; //------SDO(TxData.TBIT15); RxData.TBIT15=SDI(); SCK(1);SCK(0);SDO(TxData.TBIT14); RxData.TBIT14=SDI(); SCK(1); SDO(TxData.TBIT13); RxData.TBIT13=SDI(); SCK(0);SCK(1); SCK(0);SDO(TxData.TBIT12); RxData.TBIT12=SDI(); SCK(1); SDO(TxData.TBIT11); RxData.TBIT11=SDI(); SCK(0);SCK(1);SDO(TxData.TBIT10); SCK(0);RxData.TBIT10=SDI(); SCK(1); SDO(TxData.TBIT9); SCK(0); RxData.TBIT9=SDI(); SCK(1): SCK(0);SDO(TxData.TBIT8); RxData.TBIT8=SDI(); SCK(1); SCK(0);SDO(TxData.TBIT7); RxData.TBIT7=SDI(); SCK(1); SDO(TxData.TBIT6); SCK(0);RxData.TBIT6=SDI(); SCK(1); SCK(0);SDO(TxData.TBIT5); RxData.TBIT5=SDI(); SCK(1); SCK(0);SDO(TxData.TBIT4); RxData.TBIT4=SDI(); SCK(1): SDO(TxData.TBIT3); RxData.TBIT3=SDI(); SCK(0);SCK(1);SCK(0);SDO(TxData.TBIT2); RxData.TBIT2=SDI(); SCK(1); SCK(0);SDO(TxData.TBIT1); RxData.TBIT1=SDI(); SCK(1);SCK(0);SDO(TxData.TBIT0); RxData.TBIT0=SDI(); SCK(1); SCK(0);//-----

return (RxData.Tunsigned int);

,								
//=-=-:	=-==-	=-=-:	=-=-=-=		=-=	-=-=-=-=-=-=		
void	PUP(void)	{	CS(0);	<pre>Delay_10mS();</pre>	<pre>SendCmd(0xB100);</pre>	CS(1); }		
void	PDN(void)	{	CS(0);	<pre>Delay_10mS();</pre>	<pre>SendCmd(0xB200);</pre>	CS(1); }		
void	FORMAT(void)	{	CS(0);	<pre>Delay_10mS();</pre>	<pre>SendCmd(0xA5A5);</pre>	CS(1); }		
void	STOP(void)	{	CS(0);	<pre>Delay_10mS();</pre>	<pre>SendCmd(0x0000);</pre>	CS(1); }		
void	DELETE(unsigned int VoiceNo)	{	CS(0);	<pre>Delay_10mS();</pre>	SendCmd(0x1000 (Vo	piceNo&OxO3FF));	CS(1);	}
void	REC(unsigned int VoiceNo)	{	CS(0);	<pre>Delay_10mS();</pre>	SendCmd(0x2000 (Vo	piceNo&OxO3FF));	CS(1);	}
void	PLAY(unsigned int VoiceNo)	{	CS(0);	<pre>Delay_10mS();</pre>	SendCmd(0x30001(Vo	piceNo&OxO3FF));	CS(1);	}
//=====								
// Mai	n							
//=-=-:	=-=	=-=-:	=-=-=-=-=		=-=	-=-=-=-=-=-=		
void	main(void)							
{								
11								
In	it_IO();			// Initial	I/O: /CS=0, SCK=0,	SDI=0, SDO=inpu	t, /BUSY=i	input.
//								
wh	ile(!P_BUSY);			// Check f	or /BUSY pull-up.			
//								
//	Format chip							
FO	RMAT();							
wh	<pre>ile(P_BUSY); while(!P_BUSY);</pre>			// Wait fo	r format operation s	start & finished	•	
//								
wh	ile(1)							
{								
	if(KEY_REC)							
	{							
	DELETE(0x0000);							
	<pre>while(P_BUSY); while(!P_E</pre>	USY)	;	// Wait fo	r delete operation s	start & finished	•	
	REC(0x0000); Delay_10mS	();		// Record	the No.O voice.			
	<pre>while((KEY_REC)&(!P_BUSY))</pre>	;		// Wait fo	r release record key	y or full of mem	ory.	
	STOP();							
	<pre>while(!P_BUSY);</pre>			// Wait fo	r record finished.			
	}							
	if(KEY_PLAY)							

aPR33A3

	l		
		PLAY(0x0000); Delay_10mS();	// Play the No.0 voice.
		<pre>while((KEY_PLAY)&(!P_BUSY));</pre>	// Wait for release play key or end of voice.
		STOP();	
		<pre>while(!P_BUSY);</pre>	// Wait for play finished.
	}		
	}		
	//		
	return	;	
}			
//=			



BLOCK DIAGRAM



Figure 1. Block Diagram

■ ABSOLUTE MAXIMUM RATINGS

Symbol	Rating	Unit
VDD – VSS	-0.3 ~ +10.0	V
Vin	VSS-0.3 < VIN < VDD+0.3	V
Vout	VSS < Vout < VDD	V
T(Operating)	-40 ~ +85	°C
T(Junction)	-40 ~ +125	°C
T(Storage)	-40 ~ +125	°C

DC CHARACTERISTICS

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
VDD	Operating Voltage	3.0		6.5	V	
lsв	Standby Current			1	μA	
PDN	Power-Down Current		15	20	μA	
OP(IDLE)	Operating Current (Idle)		20		mA	VDD = 5V
OP(REC)	Operating Current (Record)		35		mA	VDD = 5V
OP(PLAY)	Operating Current (Playback)		25		mA	VDD = 5V
Vін	"H" Input Voltage	2.5			V	
VIL	"L" Input Voltage			0.6	V	
Ινουτ	VOUT Current		185		mA	
Іон	O/P High Current		8		mA	VDD = 5V / VOH=4.5V
Iol	O/P Low Current		14		mA	VDD = 5V / VOH=0.5V
RNPIO	Input pin pull-down resistance		300		KΩ	External floating or drive low.
			1		MΩ	External drive high.
Rupio	Input pin pull-up resistance		4.7		KΩ	
riangle Fs/Fs	Frequency stability			5	%	$VDD = 5V \pm 1.0V$
∆Fc/Fc	Chip to ship Eroquency Veriation			Б	%	Also apply to lot to lot
				5		variation.



AC CHARACTERISTICS



Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
T1	CS Setup Time	10			mS	VDD=5.0V
T2	Data-In Setup Time	500			nS	VDD=5.0V
Т3	Data-In Hold Time	500			nS	VDD=5.0V
T4	/CS Hold Time	500			nS	VDD=5.0V
T5	/CS High Time	10			mS	VDD=5.0V
Т6	Data-Out Setup Time			500	nS	VDD=5.0V
T7	BUSY Setup Time			10	mS	VDD=5.0V
Т8	BUSY Hold Time			10	mS	VDD=5.0V

PACKAGE INFORMATION

